

DATA SHEET

HSCDTD015A

ALPSALPINE ALPSALPINE CO., LTD.

HEAD OFFICE
1-7, YUKIGAYA-OTSUKA-MACHI, OTA-KU, TOKYO, 145-8501, JAPAN
PHONE +81(3)3726-1211 FAX +81(3)3728-1741
NAGAOKA R&D CENTER
1-3-5, HIGASHITAKAMI-MACHI, NAGAOKA-CITY, NIIGATA-PREF, 940-0006, JAPAN
PHONE +81 258-24-4111 FAX +81 258-24-4110

This specification is subject to change without notice.

History of revision

| Datasheet Rev. | Date | Page | Note |
|----------------|-------------|------|---------------------------------------|
| 1.0 | 27.Jun.2025 | | First edition |
| 1.1 | 28.Nov.2025 | P32 | Add recommended soldering conditions. |
| | | | Add Reel and Tape informations. |
| | | P33 | Add Reel and Tape informations. |

OVERVIEW

HSCDTD series is three axis terrestrial magnetism sensor of the digital output.

A high sensitivity magnetic sensor that detects the terrestrial magnetism element is mounted.

It provides with the drive circuit, the signal processing circuit, and the serial interface.

FEATURES

- 3-Axis magnetic sensor with (XYZ) 0.075 [μ T/LSB] resolution
- Output, x, y, z axis magnetic field strength.
- Serial interface
 - I2C slave interface (SS、FS、FS+) PhilipsI2C revision .2.1 and
 - NXP UM10204 I2C-bus specifications and user manual Rev.03-19 June 2007 is supported.
- 16 pin, FLGA package
- Package size : 1.6 × 1.6 x t0.64mm (Maximum size)
- Low current consumption
- Lead free, RoHS instruction, Halogen free conforming

- Function
 - Initialization Function (Power on reset)
 - Functional Mode
 - Standby Mode
 - Continuous Measurement Mode (CMM)
 - (Data Rate 10 / 50 / 100 / 200Hz Selectable)
 - One-shot Mode
 - Temperature Compensation Function
 - Data Ready Function
 - Interrupt Function
 - FIFO Function

- Supply Voltage
 - Analog 1.6 to 2.0 V
 - Digital 1.14 to 2.0 V

- Operating Temperature -40 to +85°C

ABSOLUTE MAXIMUM RATINGS

| Parameter | Symbol | Min. | Typ. | Max. | Unit |
|--|--------|------|------|------|------|
| Maximum voltage supply(AVDD/VDDIO) | Vmax | -0.5 | | 3.6 | V |
| Storage Temperature | Tstg | -40 | | +125 | °C |
| Electrostatic discharge protection @ HBM | | 1500 | | | V |
| Electrostatic discharge protection @ CDM | | 350 | | | V |

ELECTRICAL CHARACTERISTICS

Temperature condition : 25 degC

| Characteristics | | Symbol | Min. | Typ. | Max. | Unit |
|---|--|-------------------|-----------------|---------------------------|-------------------|------|
| Supply Voltage AVDD | | AVDD | 1.6 | | 2.0 | V |
| Supply Voltage DVDD | | VDDIO | 1.14 | | 2.0 | V |
| Standby Mode current | | IDAstb | | 19 | 40 | μA |
| One shot mode current | | IDAosm | | 21 | 45 | μA |
| CMM Average current consumption @ 50Hz±10% @AVDD=1.8V | TAP=6bit TAP=7bit TAP=8bit TAP=9bit | IDAlp_avg | | 84 121 196 344 | | μA |
| CMM Average current consumption @ 100Hz±10% @AVDD=1.8V | TAP=6bit TAP=7bit TAP=8bit TAP=9bit | IDAlp_avg | | 146 222 369 666 | | μA |
| CMM Average current consumption @ 200Hz±10% @AVDD=1.8V | TAP=6bit TAP=7bit TAP=8bit TAP=9bit | IDAlp_avg | | 273 420 717 1311 | | μA |
| Digital IO Low Level Input Voltage | | VIL | -0.5 | | VDDIO*0.3 | V |
| Digital IO High Level Input Voltage | | VIH | VDDIO*0.7 | | VDDIO+0.5 | V |
| Digital IO Low Level Output Voltage | | VOL | -0.5 | | VDDIO*0.3 | V |
| Digital IO High Level Output Voltage | | VOH | VDDIO*0.7 | | VDDIO | V |
| I2C Clock Frequency | Standard/Fast+ | I2Cffs | 0.1 | 0.4 | 1 | MHz |
| SPI Clock Frequency @ VDDIO=1.8V | | SPIf | | 12 | 20 | MHz |
| TRG pull-down resistance | VDDIO = 1.14 V VDDIO = 1.8 V VDDIO = 2.0 V | R _{TRG} | 230 70 50 | 373 114 94 | 570 180 150 | kohm |
| TRG input pulse width (active high) | | PW _{TRG} | 20 | | | μsec |
| INT pull-up resistance (Open-drain setting only) | VDDIO = 1.14 V VDDIO = 1.8 V VDDIO = 2.0 V | R _{INT} | 167 64 55 | 266 98 83 | 401 145 122 | kohm |

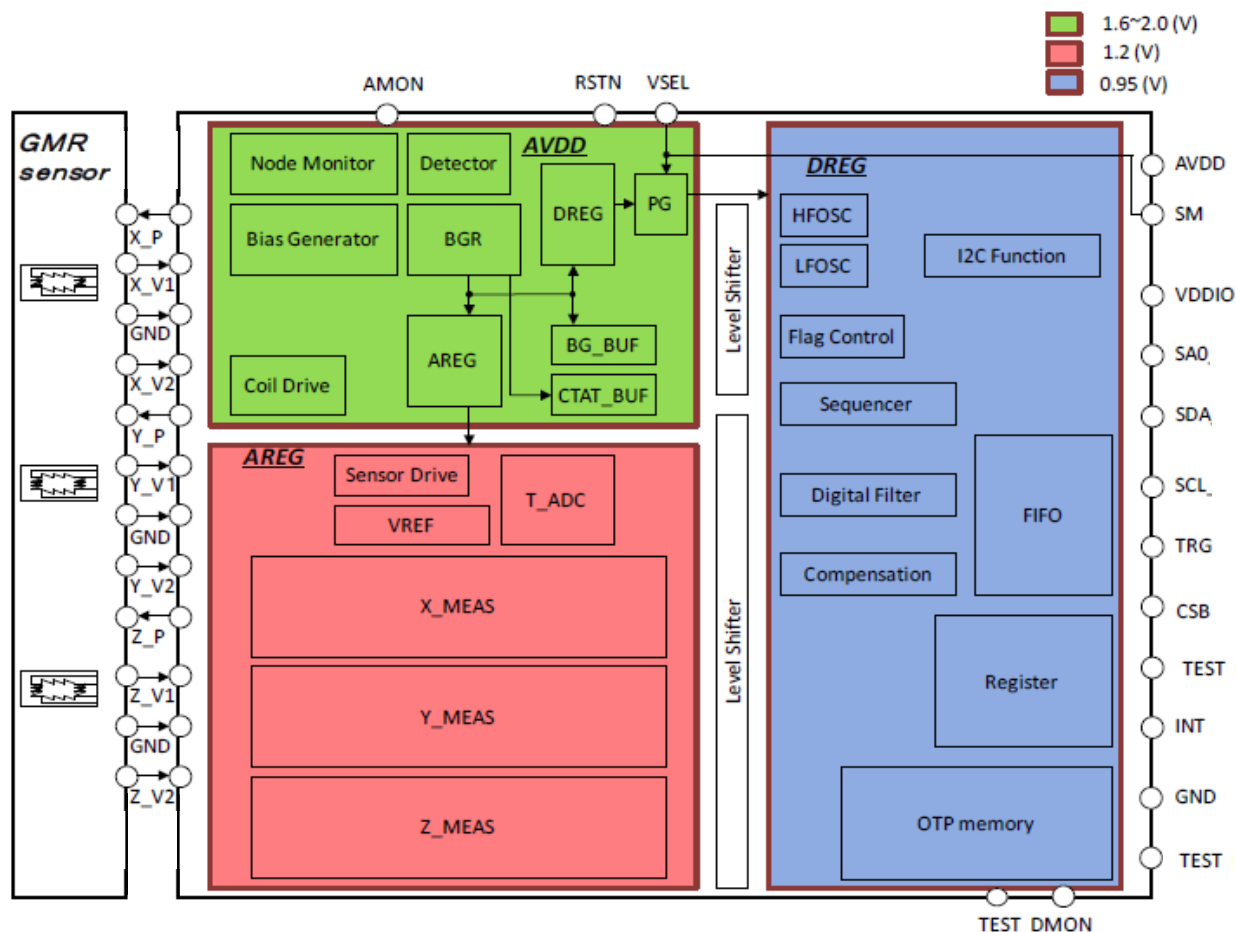
MAGNETIC CHARACTERISTICS

Temperature condition : 25 degC

| Characteristics | | | Symbol | Min. | Typ. | Max. | Unit |
|--|-----------------|--|--------------|-------|----------------------------------|----------|--------|
| Operating Temperature | | | Ta | -40 | | +85 | °C |
| Full Scale Range, Magnetic field measuement | | | FSmag | -2.4 | | +2.4 | mT |
| Sensitivity Error | | | Smag,err | -2.5 | | 2.5 | % |
| Resolution | | | Res | 0.073 | 0.075 | 0.077 | μT/LSB |
| Temperature Resolution | | | TPres | | 0.03125 | | °C/LSB |
| RMS Noise | CMM TAP=7bit | X | Nmag,rms | | 0.09 | 0.17(※1) | μT |
| | | Y | | | 0.10 | 0.17(※1) | |
| | | Z | | | 0.11 | 0.17(※1) | |
| | CMM TAP=8bit | X | | | 0.08 | | |
| | | Y | | | 0.09 | | |
| | | Z | | | 0.10 | | |
| | CMM TAP=9bit | X | | | 0.07 | | |
| | | Y | | | 0.08 | | |
| | | Z | | | 0.09 | | |
| Output Data Rate | | ODR=00 ODR=01 ODR=10 ODR=11 | ODRmag | | 200 100 50 10 | | Hz |
| CMM Meas Time | | TAP=6bit TAP=7bit TAP=8bit TAP=9bit | MTlpm | | 0.310 0.502 0.886 1.654 | | msec |
| Temperature Measurement Time | | TAP=5bit | MTts | | 126 | | μsec |
| | | TAP=6bit | | | 174 | | μsec |
| Software Reset Time | | | Tsrst | | 165 | 180 | μsec |
| Zero-field Offset Variation over Temperature | | | ΔOSmag,t | -0.1 | | 0.1 | μT/°C |
| Sensitivity Error over Temperature | | | Smag,err,t | 0.0 | | 2.5 | % |
| Sensitivity Error Mismatch between axes | | | Smag,err,mis | -1.0 | | 1.0 | % |
| Nonlinearity | | | Lmag | 0.0 | | 2.0 | % |
| Hysteresis @ ±1.2mT | | | Hys | | | 2.0 | uT |

(※1) Noise inspection is performed with TAP=7 bit only and Max value is inspection Spec.

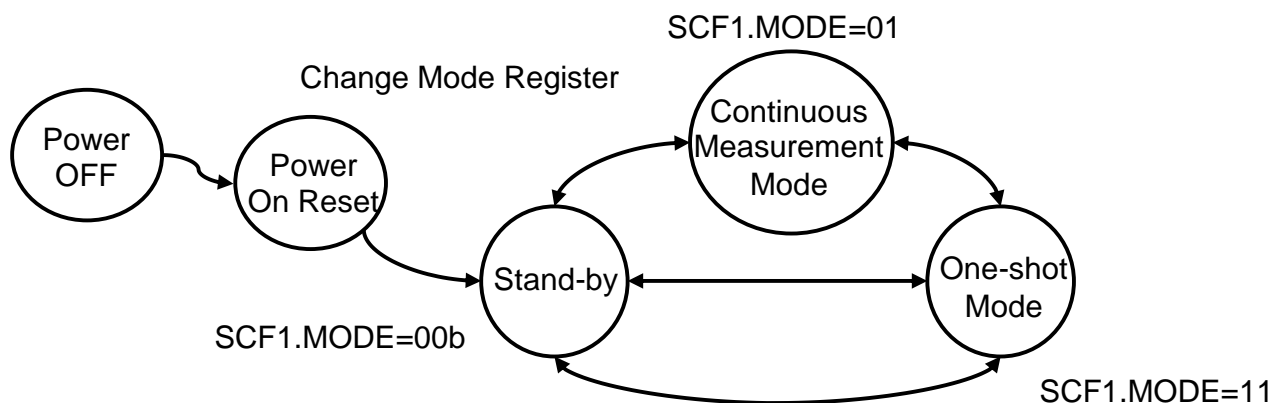
BLOCK DIAGRAM



FUNCTIONAL SPECIFICATIONS

Function List

| Name | Description |
|-----------------------------------|--|
| Initialization | Power on reset is performed by turning on the power. All circuits and registers are set to default and mode is set to Standby Mode automatically by POR. Software reset is performed by writing to control register. All register except OTP register is set initial value. |
| Functional Modes | This sensor has Standby Mode and active mode for power control. There are 2 states in active mode. |
| Off mode | The sensor is not active when AVDD or VDDIO is disable. |
| Standby Mode | Low power waiting state. Standby Mode can access to register. |
| Active Mode | Change from Standby Mode to active mode by register command to Sensor Config1 register. |
| Continuous Measurement Mode (CMM) | Continuous interval measurement. Interval time depends on ODR setting. |
| One-shot Mode (OSM) | External Trigger Measurement / Register Action Measurement Measruemet is same as CMM setting |
| Interrupt Function | Measurement event |
| Data Ready function | Informs when new measured results are updated. It is possible that data ready inform the signal to the DRDY pin when updated output data. |
| FIFO Threshold function | Informs when FCNT is greater than or equal to FFTH. |
| FIFO Full function | Informs when all 64 data are stored in the FIFO. |
| POR event function | Informs when POR is completed. |
| SRST event function | Informs when SRST is completed. |
| Temperature Measurement Function | Retrieve temperature data from internal temperature sensor. Temperature data is used for internal compensation for output data. |
| Temperature Compensation Function | Compensate gain and offset in digital circuit by temperature measurement results. |



State Machine

FUNCTIONAL SPECIFICATIONS (Continued)

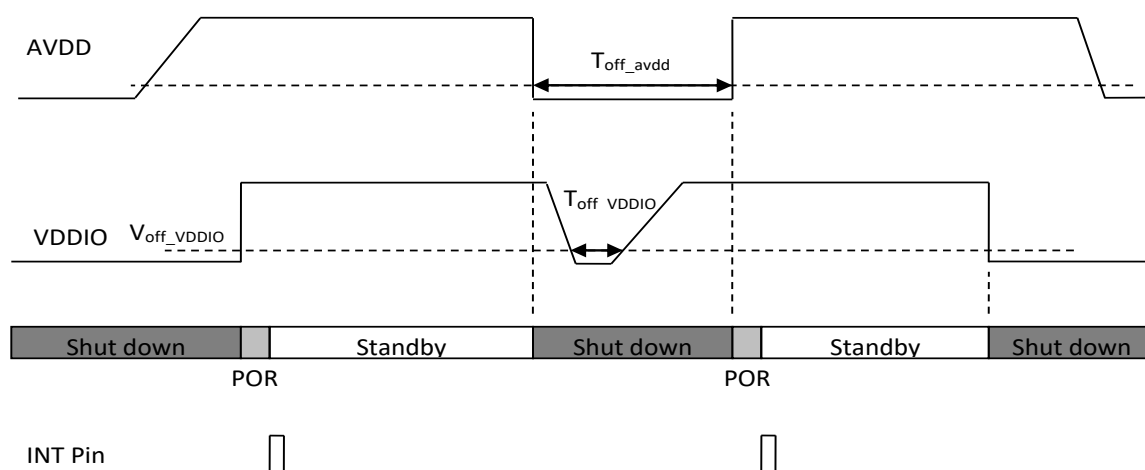
Initialization

- All internal circuits and all register values are initialized with POR (Power On Reset) after power-on.
- After initialization, the functional mode move to Standby Mode automatically.
- The software reset set by the register command /CCF.SRST=1 makes all register value to defaults.

Supply Power Specifications

Supply power sequence

- Supply power sequence for AVDD and VDDIO shall not be limited.
However, Ramp Time shall be satisfied 0.01 ~ 3 ms at the 10% ~ 90% range of the voltage.
- Reset is extended for 192 clocks of LFOSC count after detection of AVDD and VDDIO voltage.
And then, it shall release the Reset if AVDD voltage and VDDIO are available.
- Supply power sequence read OTP after Reset release, and output pulse signal from INT pin, and then transit to Standby Mode.



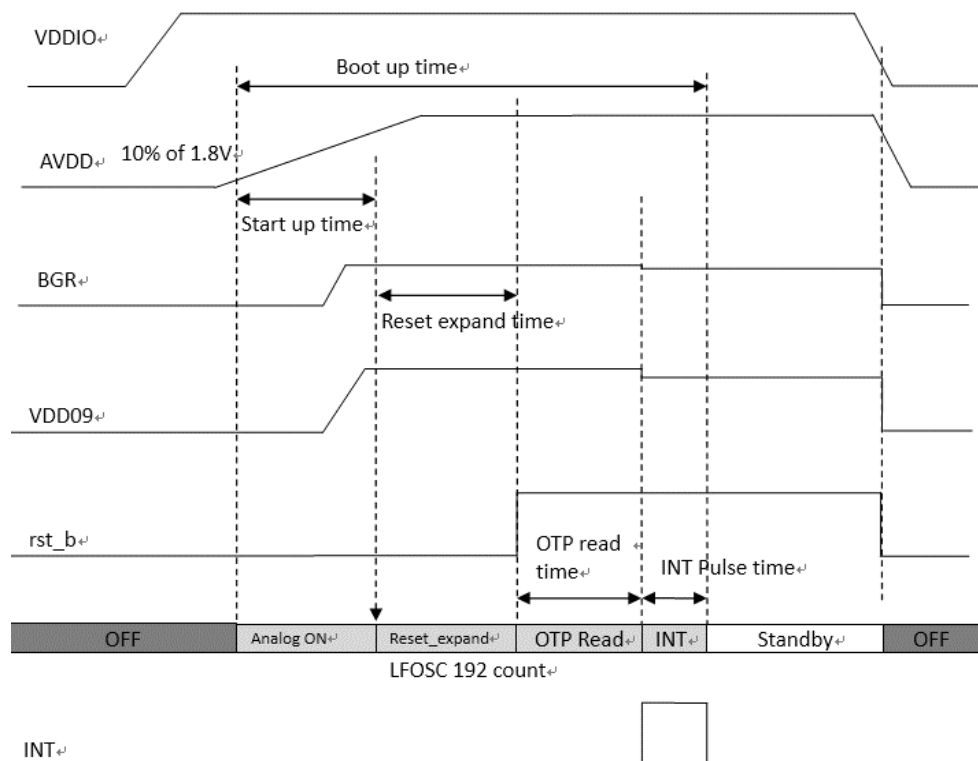
Power ON/OFF Sequence

Shut-down specifications

| Parameters | Symbols | Conditions | Characteristics | | | Units |
|------------------------|------------------|------------|-----------------|-----|-----|-------|
| | | | MIN | TYP | MAX | |
| AVDD Shut Off voltage | V_{off_AVDD} | | 0 | | 0.3 | V |
| VDDIO Shut Off voltage | V_{off_VDDIO} | | 0 | | 0.3 | V |
| AVDD Shut Off time | T_{off_AVDD} | | 0.1 | | | msec |
| VDDIO Shut Off time | T_{off_VDDIO} | | 0.1 | | | msec |

FUNCTIONAL SPECIFICATIONS (Continued)
Supply Power Specifications (Continued)
Power operation

- Power Operation detects power line voltage in ASIC after AVDD and VDDIO were supplied, and make LFOSC work, and extend Reset 192 clock.
 - Power Operation reads OTP after Reset extension, then transit to Standby Mode.
- It shall not allow the access by I/F during this operation.


Power On Sequence
Power On Sequence Specifications

| Parameters | Symbols | Conditions | Characteristics | | | Units |
|---------------------|----------------|-----------------------------|-----------------|-----|-------|-------|
| | | | MIN | TYP | MAX | |
| Power rise time | T_{Prise} | 10% - 90% | 0.01 | | 3 | msec |
| Power fall time | T_{Pfall} | 10% - 90% | 0.1 | | 3 | msec |
| Start up time | T_{start} | 10% to rest release | 1.4 | | 2.2 | msec |
| Reset_expander time | T_{rexp} | | 0.89 | | 1.4 | msec |
| OTP read 64 Byte | $T_{OTPread}$ | | | 100 | 200 | usec |
| INT pulse time | T_{INT_POR} | | 148.5 | 165 | 181.5 | usec |
| Boot-up time | T_{bootup} | From 10% of 1.8V to Standby | | | 4 | msec |

FUNCTIONAL SPECIFICATIONS (Continued)

Modes

OFF mode

- The sensor is not active when AVDD or VDDIO is disable.

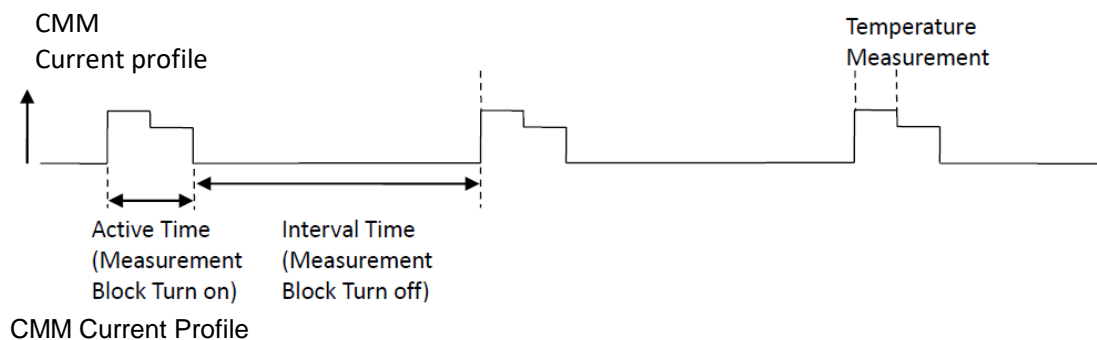
Standby Mode

- After loading the POR (Power On Reset), internal state is moved to Standby Mode automatically.
- Standby Mode is set by the register command /SCF1.MODE=00b.

Active Mode

Continuous Measurement Mode [CMM]

- Continuous Measurement Mode is set by the register command /SCF1.MODE=01b.
- After the measurement is completed, the measurement circuit is shut down to maintain low current consumption.
- X, Y, Z axis and temperature measurement is simultaneously performed
- Measure automatically according to the set Output Data Rate (ODR).
- Temperature compensation is performed automatically by measurement with a temperature sensor.

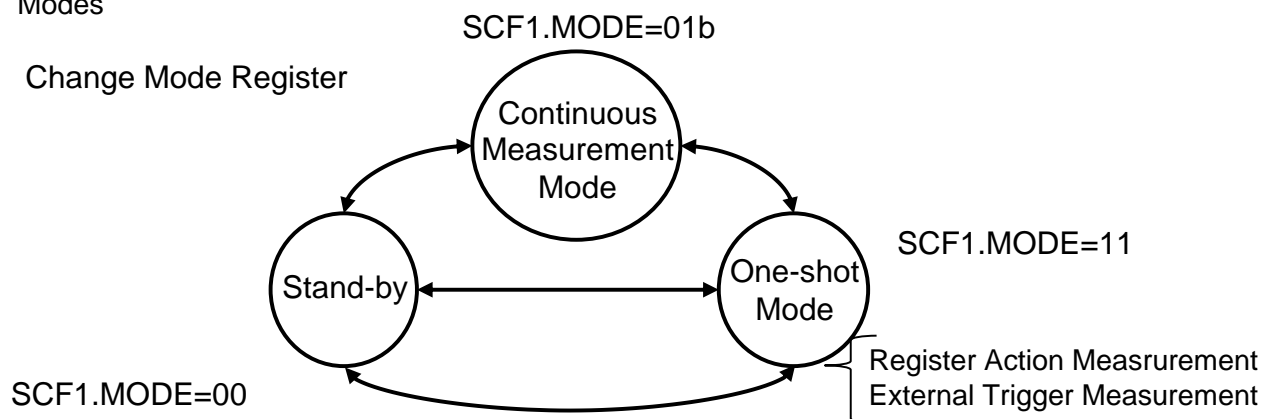


One-shot Mode

- One-shot Mode is set by the register command /SCF1.MODE=11b.
- Register Action Measurement is performed by accessing the register /SACT.MES=1b.
- External Trigger Measurement is performed by inputting the pulse into the TRG terminal.
- Measurement setting is the same setting as CMM.

Modes

Change Mode Register



The diagram on mode transfer

FUNCTIONAL SPECIFICATIONS (Continued)

Register configuration

Register configuration change behavior

- In case of changing register related measurement, the measurement shall be started with new configuration after writing completion.
- In case during measurement, analog circuit shall be reset, and then start measurement with new conditions.
- In case of OneShotMode, measurement shall be ended, and no new measurement shall be started automatically.

Register configuration behavior

| Register | bit | Description | Mode | Measure | FIFO | Status | INT pin |
|----------|--------------|--|------------|------------------|-------|-------------------------|--------------------|
| CCF | SRST | Software Reset | All | clear | clear | clear | clear |
| ISO | DRDY | Data Ready | CMM | - | - | - | clear or re-assert |
| | FTHS FFUL | FIFO Threshold FIFO Full | OSM | - | - | - | - |
| FFCF | FFMD | FFMD=00b : BypassMode , FIFO, /ISTA.FFHR, /ISTA.FFUL Clear | CMM OSM | - | clear | clear FTHS & FFUL | clear or re-asser |
| | FFTH | FIFO Count FCNT>=FFTH : assert | CMM OSM | - | - | clear or re-assert | clear or re-assert |
| SCF1 | TDIS | TEMP Disable | CMM | clear & re-start | - | - | - |
| | RES | Resolution Select | OSM | clear | - | - | - |
| | TAP[1:0] | Mesure TAP | CMM | clear & re-start | - | - | - |
| | ODR[1:0] | Output Data Rate | OSM | clear | - | - | - |
| | MODE[1:0] | Change CMM | CMM | clear & re-start | - | - | - |
| | | MODE=11b OSM | OSM | clear | - | - | - |
| | | MODE=00b (Stand-by) | STB | clear | clear | clear | clear |

FUNCTIONAL SPECIFICATIONS (Continued)

FIFO event function (Continued)

FIFO Data

There are 64 count for FIFO and it consists of reserved 8 Bytes and TEMP 2 Bytes and MAG 6Bytes.

The reading of FIFO is done by register address 27h.

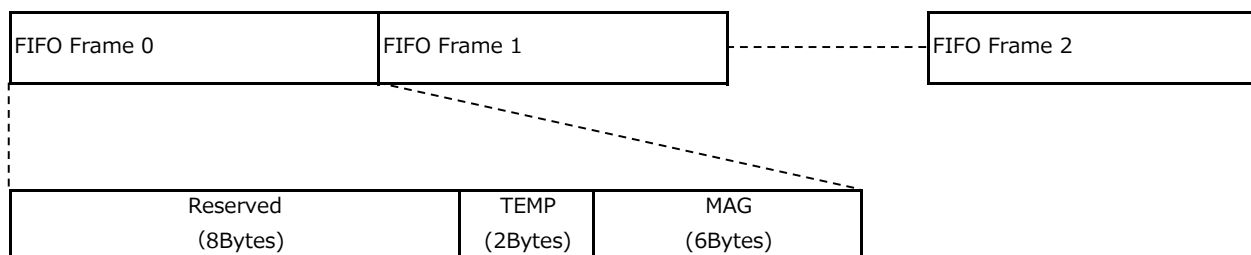


図11 : FIFO Frame Description

FIFO frame description

FIFO structure

| Pin Structure | | | | | | | | | | | |
|---------------|----------------------|-----------------|------|------|------|------|------|------|------|--|-------|
| Number | Register Name | Bit information | | | | | | | | | empty |
| | | bit7 | bit6 | bit5 | bit4 | bit3 | bit2 | bit1 | bit0 | | |
| Byte0 | Reserved | - | | | | | | | | | - |
| Byte1 | | | | | | | | | | | |
| Byte2 | | | | | | | | | | | |
| Byte3 | | | | | | | | | | | |
| Byte4 | | | | | | | | | | | |
| Byte5 | | | | | | | | | | | |
| Byte6 | | | | | | | | | | | |
| Byte7 | | | | | | | | | | | |
| Byte8 | Temperature Data LSB | TEMP[7:0] | | | | | | | | | 7Fh |
| Byte9 | Temperature Data MSB | TEMP[15:8] | | | | | | | | | 7Fh |
| Byte10 | X Magnetic Data LSB | MAGX[7:0] | | | | | | | | | 7Fh |
| Byte11 | X Magnetic Data MSB | MAGX[15:8] | | | | | | | | | 7Fh |
| Byte12 | Y Magnetic Data LSB | MAGY[7:0] | | | | | | | | | 7Fh |
| Byte13 | Y Magnetic Data MSB | MAGY[15:8] | | | | | | | | | 7Fh |
| Byte14 | Z Magnetic Data LSB | MAGZ[7:0] | | | | | | | | | 7Fh |
| Byte15 | Z Magnetic Data MSB | MAGZ[15:8] | | | | | | | | | 7Fh |

FUNCTIONAL SPECIFICATIONS (Continued)

Interrupt function

Interrupt Source

INT source list

| Type | bit | Condition | Status bit |
|----------|---------------------------|--|------------|
| ISO.DRDY | 1:selected 0:no action | INT is active High when DATA is set in DATA_REG after measurement | ISTA.DRDY |
| ISO.FTHS | 1:selected 0:no action | INT is atctive when FIFO is over FFCF.FFTH. - FIFO_COUNT = FFTH after measurement - FIFO_COUNT ≥ FFTH after reading FIFO | ISTA.FTHS |
| ISO.FFUL | 1:selected 0:no action | INT is active when FIFO is 64 count. - when FIFO_COUNT=63 is changed to FIFO_COUNT=64 | ISTA.FFUL |
| POR | Always active | INT is active(pulse) after power on reset | ISTA.POR |
| CCF.SRST | Always active | INT is active(pulse) after software reset | ISTA.POR |

Interrupt Status Clear Event

Interrupt Status Clear Condition

| Status bit | Trigger | Clear Condition | Description |
|------------|-----------------|-----------------------|---------------------------|
| ISTA.DRDY | End of Meas | Read / ISTA | Read Status Byte(ADR;25h) |
| | | Write / SCF1.MODE=00b | Change Standby Mode |
| ISTA.FTHS | FCNT>=FFTH | Read / ISTA | Read Status Byte(ADR;25h) |
| | | Write / SCF1.MODE=00b | Change Standby Mode |
| | | Write / FFCF.FFMD=00b | Change Bypass Mode |
| ISTA.FFUL | FCNT=63->64 | Read / ISTA | Read Status Byte(ADR;25h) |
| | | Write / SCF1.MODE=00b | Change Standby Mode |
| | | Write / FFCF.FFMD=00b | Change Bypass Mode |
| ISTA.POR | End of POR/SRST | Read / ISTA | Read Status Byte(ADR;25h) |

Note) Software reset : All clear, after software reset completion, ISTA.POR is asserted

FUNCTIONAL SPECIFICATIONS (Continued)

Interrupt function (Continued)

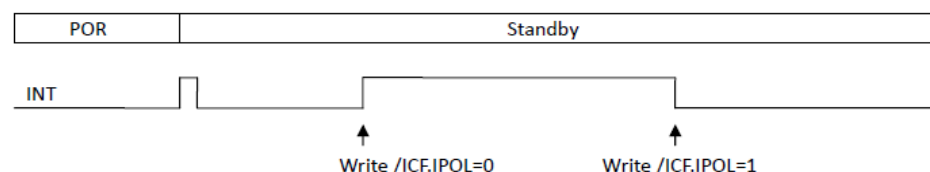
FIFO Threshold Interrupts (Continued)

Interrupt Pin Behavior

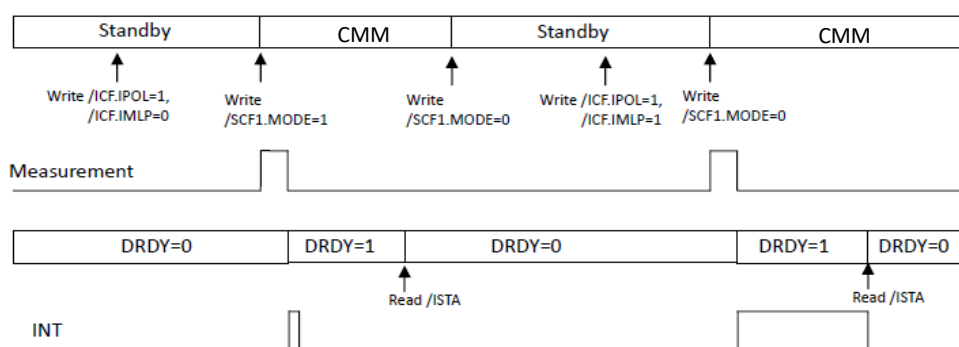
- INT Pin support Pulse Mode and Latch Mode for each interrupt function, it can be controlled for each register of /ICF.
- The following table shows each condition.
- In the case of Pulse Mode, it certainly keep inactivate term after the signal activate.
- If /ICF.IPOL=1, INT Pin must Active High. If /ICF.IPOL=0, INT Pin must Active Low.
- If /ICF register was changed in CMM and OSM Mod, the function can NOT be guaranteed. /ICF should be changed in Standby Mode.

Interrupt Pin Configuration

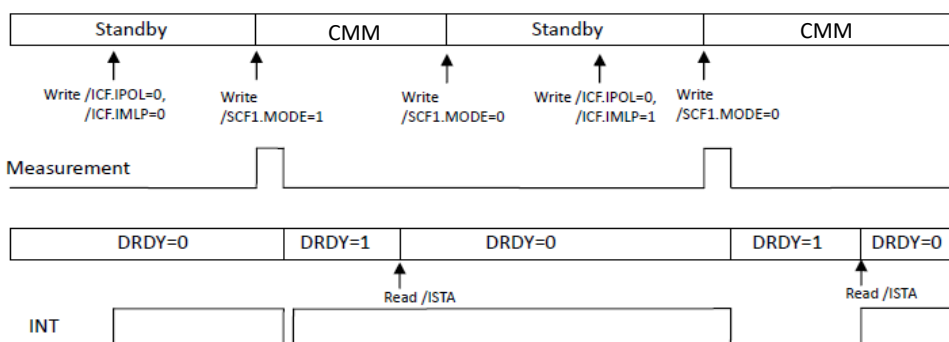
| /ICF | Default | Description | bits |
|------|---------|----------------------------|-----------------------------------|
| IMLP | 0 | INT Signal Mode | 1: Latched Mode 0 : Pulse Mode |
| IPPO | 1 | INT PAD type configuration | 1 : Push-Pull 0 : Open drain |
| IPOL | 1 | INT Signal Polarity | 1 : Active High 0 : Active Low |



INT polarity control on Standby Mode



INT Pulse and Latch Mode Active High



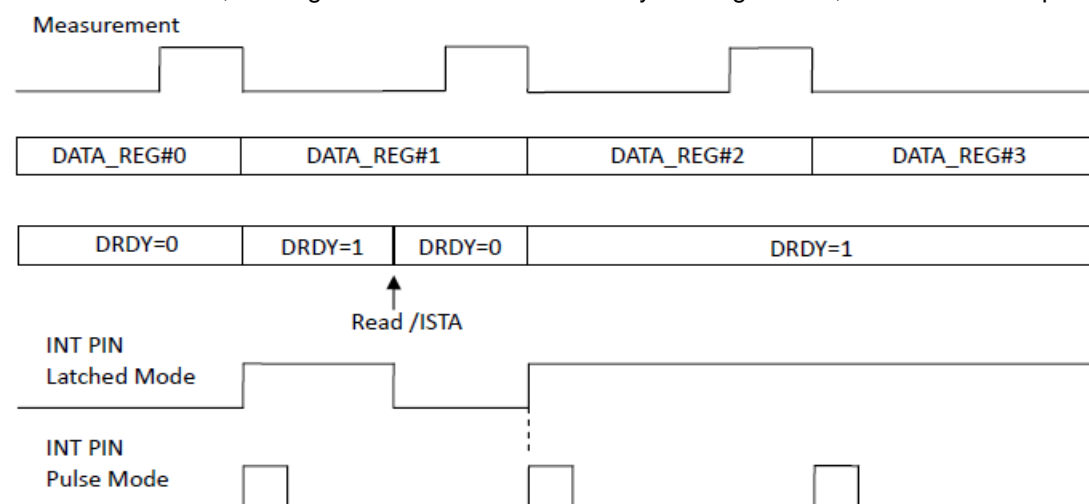
INT pulse and Latch Mode Active Low

FUNCTIONAL SPECIFICATIONS (Continued)

Interrupt Function

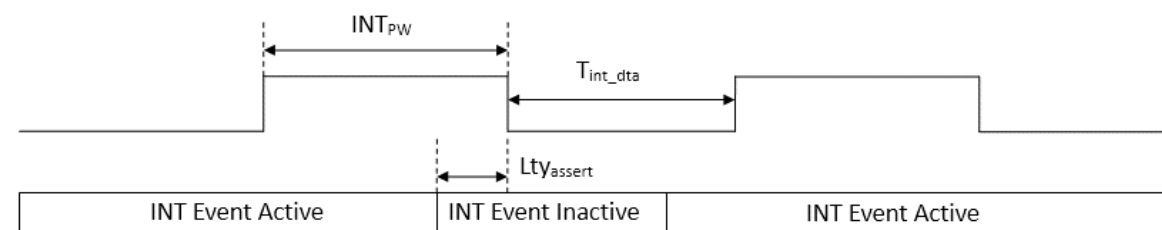
Data ready interrupt (DRDY)

- This function is used for notice that output data was updated.
- It is possible that data ready inform the signal to the INT pin when updated output data.
- In Pulse Mode, when DATA_REG is updated, the output of the INT terminal is always output.
- In Latched Mode, as long as DRDY is not released by reading / ISTA, INT terminal keeps active state.



INT standard behavior of DRDY

Interrupt Pin Timing Specifications



INT pin specifications

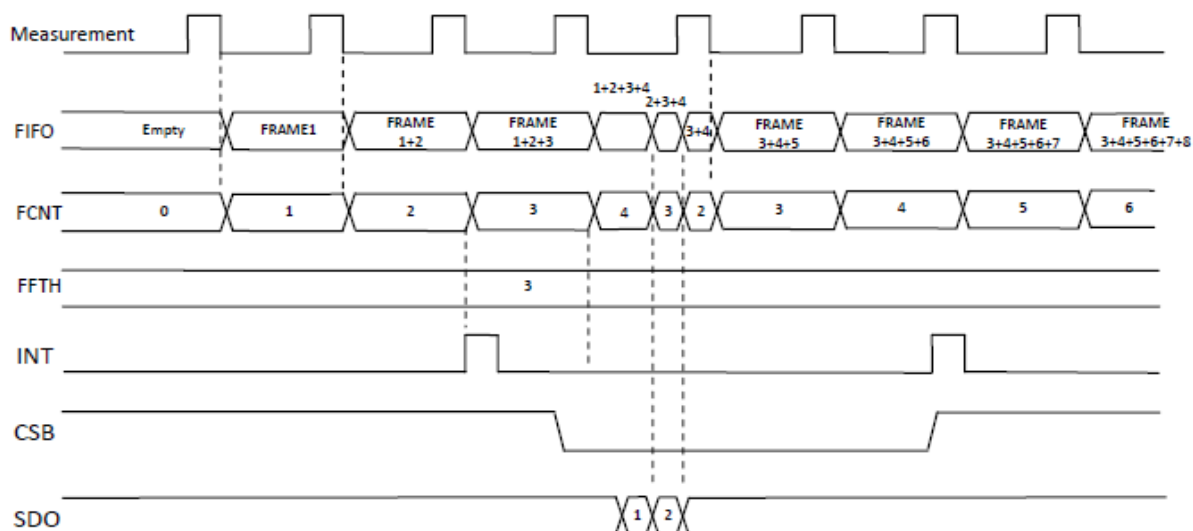
| Parameter | Symbol | Characteristics | | | Units |
|--|----------------|-----------------|-----|-------|-------|
| | | MIN | TYP | MAX | |
| Interrupt pulse width | INT_{PW} | 148.5 | 165 | 181.5 | usec |
| Time between interrupt de-assertion and re-assertion | T_{int_dta} | 139.5 | 155 | 170.5 | usec |
| De-assertion Latency | Lty_{assert} | 0 | | 20 | usec |

FUNCTIONAL SPECIFICATIONS (Continued)

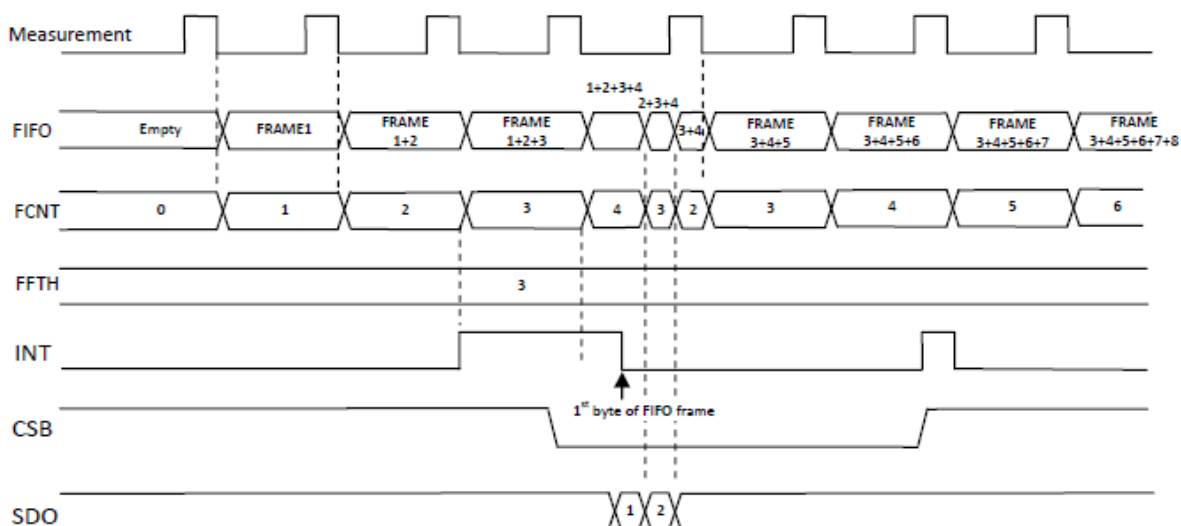
Interrupt Function (Continued)

FIFO Threshold Interrupts

- This function is used for notice that FCNT is greater than or equal to FFTH /. $ISTA.FTHS = 1$.
- If FCNT becomes FFTH or higher again during reading of FIFO data,
- INT signal is outputted from INT terminal at de-assertion of CSB (at the end of Read).



INT pulse mode behavior of FIFO Threshold Event



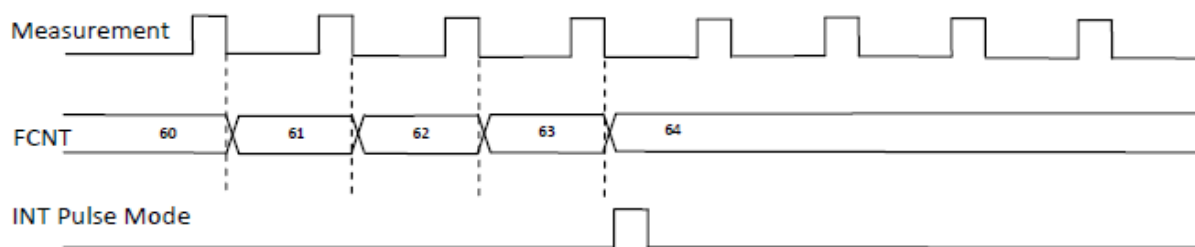
INT latch mode behavior of FIFO Threshold Event

FUNCTIONAL SPECIFICATIONS (Continued)

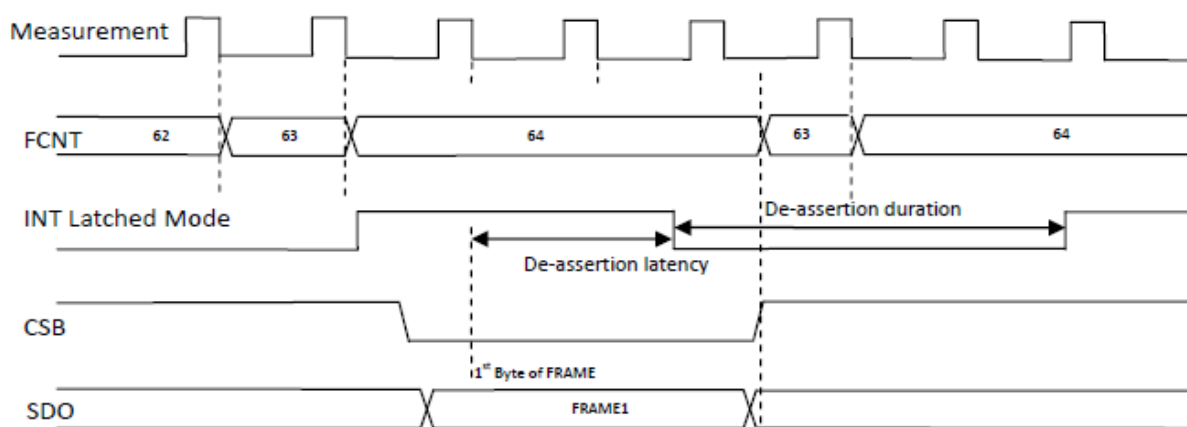
Interrupt Function (Continued)

FIFO Full Interrupts

- This function is used for notice that all 64 data are stored in the FIFO.



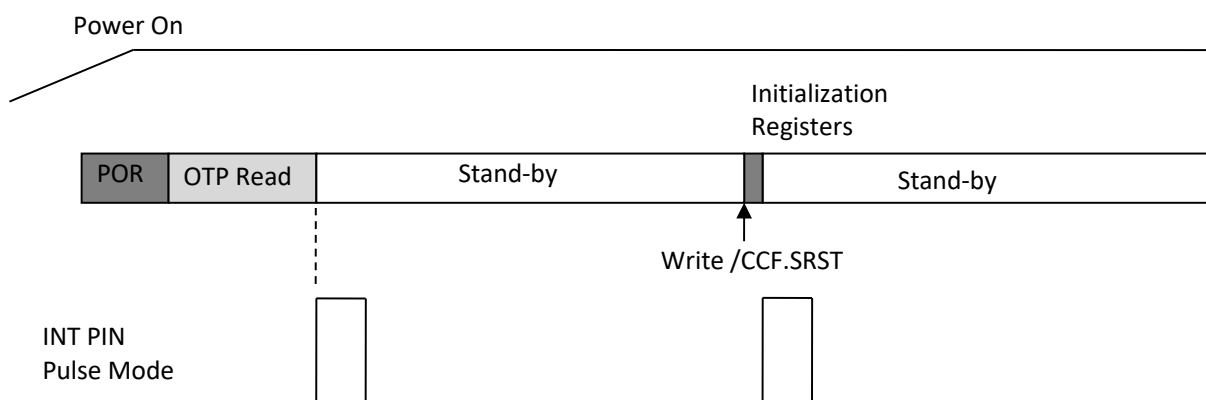
INT behavior of FIFO Full Event



INT Latched Mode behavior of FIFO Full Event

POR Interrupts / SRST Interrupts

- This function is used for notice that power-on OTP Reading or Software Reset is completed.
- Signal from INT terminal with Pulse and set / ISTA.POR = 1.

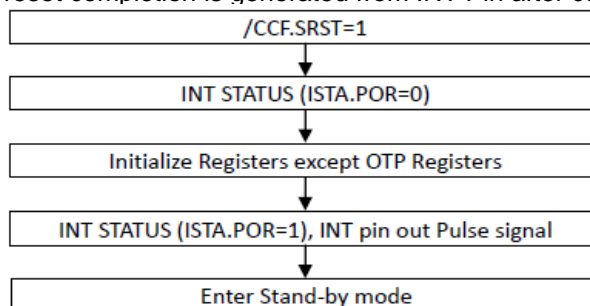


FUNCTIONAL SPECIFICATIONS (Continued)

Interrupt Function (Continued)

Software Reset

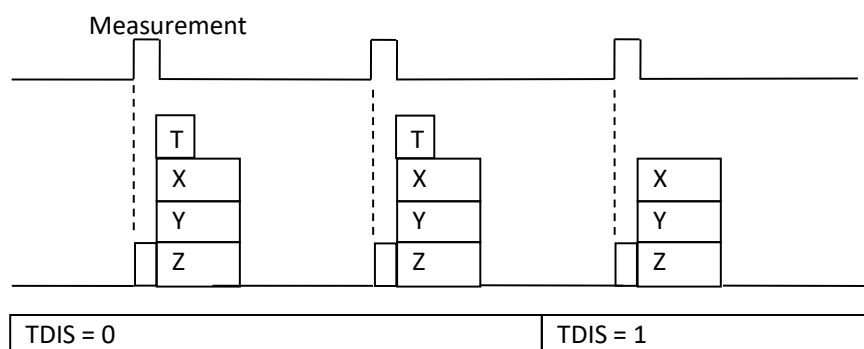
- Software reset is executed by /CCF.SRST=1.
- If software reset is executed in measurement, the measurement stops immediately and reset is executed.
- The registers get to be default value by software reset except OTP.
- The pulse signal of reset completion is generated from INT Pin after completion of software reset.



Software Reset Flow

Temperature Measurement

- The temperature measurement will be executed automatically together with magnetometer measurement in CMM & OSM mode, provided that SCF1/TDIS=0.
- Temperature only measurement can be executed only in TMES of One-shot Mode.
And only the temperature data is updated to the FIFO, and MAGX, MAGY, MAGZ are all 7 Fh.
- When / SCF1.TDIS = 1, temperature measurement does not performed in each mode.
- When / SCF1.TDIS = 0, temperature measurement is performed simultaneously with magnetic field measurement in all modes.



TDIS (Temp Measurement Disable) Function

INTERFACE SPECIFICATIONS I2C

Interface specifications

| OP53.IFS | I/F | SA0 | CSB | Description |
|----------|-----|-------|--------------|---|
| 1 | I2C | Input | Output(High) | 2 wire I2C, Standard / Fast / Fast Plus |

Register write constraints

- 71.5us interval of writing into the same configuration register
- In case of I2C, it shall be specified the time(t_{i2c_sptwd}) from StopCondition to data write of next communication.
- To the same way, writing data at the latest communication shall be written to specified register address untill StopCondition enabled in case of the communication was continued by Restart(Repeated start)Condition.

Specific Register for Configuration

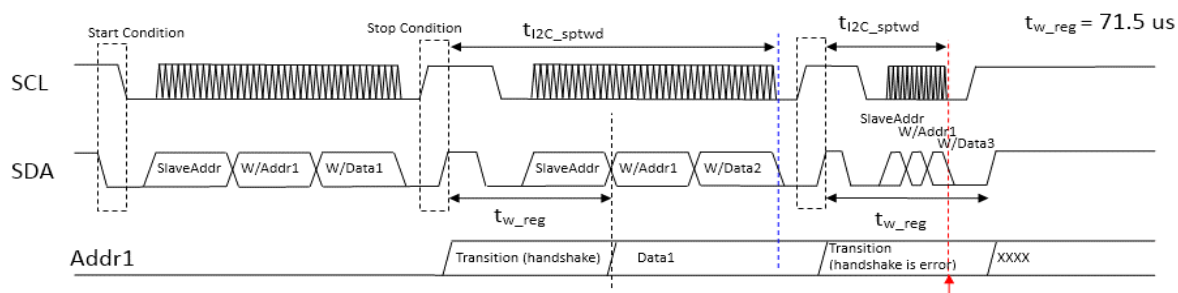
| Addr | Symbol | Name | Description |
|------|--------|----------------|---------------------------|
| 15h | ISO | INT Source | Interrupt Source Setting |
| 16h | FFCF | FIFO Config | FIFO mode, FIFO threshold |
| 17h | SCF1 | Sensor Config1 | TAP, Mode, ODR |

Interval time

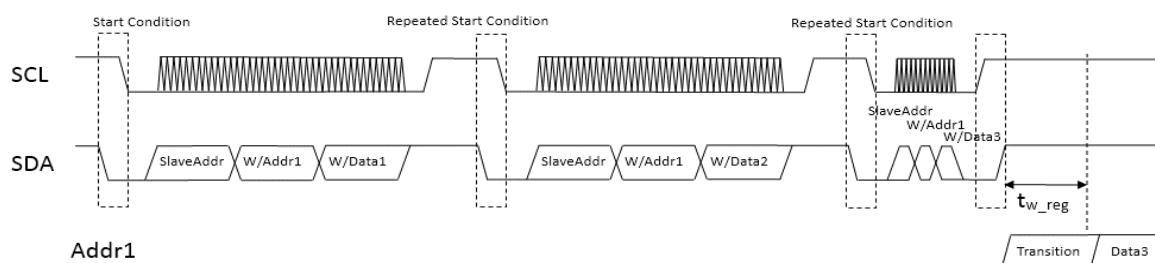
| Parameter | Symbol | Condition | Characteristics | | | Units |
|---|------------------|---------------|-----------------|-----|-----|-------|
| | | | MIN | TYP | MAX | |
| Interval time from Stop Condition to Write Data of same address | t_{i2c_sptwd} | All Condition | 71.5 | | | us |

INTERFACE SPECIFICATIONS I2C (Continued)

Register write constraints (Continued)



I²C Specific Register Write Constraints



I²C Repeated Start Condition Write to Same Register

Communication Frequency Constraints

- There is a possibility to lose the data under 1kHz for I2C, since next measurement data update is done during data reading.

Communication Frequency Constraints

| I/F | ODR | Data Period | Constraints | Min Frequency |
|------------------|-------|-------------|--------------|---------------|
| I ² C | 100Hz | 10ms | 5 SCL < 10ms | 0.5kHz |
| I ² C | 200Hz | 5ms | 5 SCL < 5ms | 1kHz |

INTERFACE SPECIFICATIONS I2C (Continued)

I2C SLAVE INTERFACE

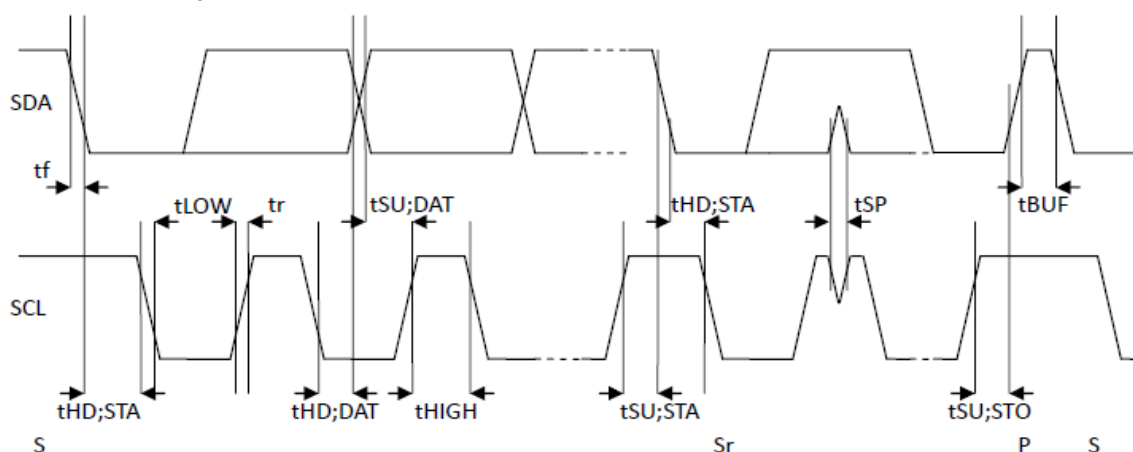
- Conformable to Philips I2C-Bus Specifications Version 2.1 and NXP UM10204 I2C-bus specification and user manual Rev.03-19 June 2007
- Slave address is SA0=0 : 0E(Hex), SA0=1 : 0F(Hex)
- Support Standard mode, Fast mode and Fast mode Plus.
- It is seamless change from Fast mode to High speed mode to use the master code (00001XXX)

I2C Characteristics

I2C Bus Timing1

| Parameters | Symbol | Standard Mode | | Fast mode | | Fast mode Plus | | Unit |
|--|--------------|----------------------|-------|----------------------|------|----------------------|------|------|
| | | Min. | Max. | Min. | Max. | Min. | Max. | |
| SCL clock frequency | f_{SCL} | 0 | 100 | 0 | 400 | 0 | 1000 | kHz |
| Hold time (re)start condition | $t_{HD;STA}$ | 4.0 | - | 0.6 | - | 0.26 | - | us |
| Low period of the SCL clock | t_{LOW} | 4.7 | - | 1.3 | - | 0.5 | - | us |
| High period of the SCL clock | t_{HIGH} | 4 | - | 0.6 | - | 0.26 | - | us |
| Set-up time for (re)start condition | $t_{SU;STA}$ | 4.7 | - | 0.6 | - | 0.26 | - | us |
| Data hold time | $t_{HD;DAT}$ | 0 | - | 0 | - | 0 | - | us |
| Data set-up time | $t_{SU;DAT}$ | 250 | - | 100 | - | 50 | - | ns |
| Rise time of SDA and SCL | t_r | 600 | 1000 | 180 | 300 | 72 | 120 | ns |
| Fall time of SDA and SCL | t_f | 6.5 | 106.5 | 6.5 | 300 | 6.5 | 81.5 | ns |
| Set-up time for stop condition | $t_{SU;STO}$ | 4.0 | - | 0.6 | - | 0.26 | - | us |
| Bus free time between a stop and start condition | t_{BUF} | 4.7 | - | 1.3 | - | 0.5 | - | us |
| Capacitive load for SDA/SCL | C_b | - | 400 | - | 400 | - | 300 | pF |
| Data valid time | $t_{VD;DAT}$ | 0.07 | 3.45 | 0.07 | 0.9 | 0.07 | 0.45 | us |
| Data valid acknowledge time | $t_{VD;ACK}$ | 0.07 | 3.45 | 0.07 | 0.9 | 0.07 | 0.45 | us |
| Noise margin at the low level | V_{nL} | $0.1 \cdot V_{DDIO}$ | - | $0.1 \cdot V_{DDIO}$ | - | $0.1 \cdot V_{DDIO}$ | - | V |
| Noise margin at the high level | V_{nH} | $0.2 \cdot V_{DDIO}$ | - | $0.2 \cdot V_{DDIO}$ | - | $0.2 \cdot V_{DDIO}$ | - | V |
| Hysteresis input voltage $V_{DDIO} < 2V$ | V_{hys} | $0.1 \cdot V_{DDIO}$ | - | $0.1 \cdot V_{DDIO}$ | - | $0.1 \cdot V_{DDIO}$ | - | V |
| Noise suppression pulse width | t_{SP} | 50 | - | 50 | - | 50 | - | ns |
| I2C Glitch Suppression | I^2C_{GS} | 150 | 200 | 150 | 200 | 150 | 200 | mV |

I2C Bus Timing



INTERFACE SPECIFICATIONS I2C (Continued)

I2C SLAVE INTERFACE (Continued)

- Data transfers follow the combined format with 7-bit addressing of I2C interface.
- Data is transferred with the most significant bit (MSB) first and little endian.
- Auto-increment of previous accessed register address is available when the internal register address is written during the first data byte. Data then can be transferred continuously.

Bus protocol definitions

S: Start condition
 SAD+W: Slave Address + write bit
 SAD+R: Slave Address + read bit
 SAD+R/W: Slave Address + read or write bit
 SA: Slave Acknowledge
 ADR: Register Address(2nd byte)
 Sr: Repeat Start condition
 A: (Master) Acknowledge
 /A: (Master) Non-Acknowledge
 DATA: Data(load)
 P: Stop condition
 M-code: Master code (00001XXX)

Read Formats

One Byte Read

| | | | | | | |
|--------|---|-------|----|-----|----|---|
| Master | S | SAD+W | | ADR | | P |
| Slave | | | SA | | SA | |

| | | | | | | |
|--------|---|-------|----|------|----|---|
| Master | S | SAD+R | | | /A | P |
| Slave | | | SA | DATA | | |

One Byte Read with repeat start condition

| | | | | | | | | | | | |
|--------|---|-------|----|-----|----|----|-------|----|------|----|---|
| Master | S | SAD+W | | ADR | | Sr | SAD+R | | | /A | P |
| Slave | | | SA | | SA | | | SA | DATA | | |

Multiple Bytes Read

| | | | | | | |
|--------|---|-------|----|-----|----|---|
| Master | S | SAD+W | | ADR | | P |
| Slave | | | SA | | SA | |

| | | | | | | | | | | |
|--------|---|-------|----|------|---|------|---|------|----|---|
| Master | S | SAD+R | | | A | | A | | /A | P |
| Slave | | | SA | DATA | | DATA | | DATA | | |

Multiple Bytes Read with repeat start condition

| | | | | | | | | | | |
|--------|---|-------|----|-----|----|----|-------|----|------|---|
| Master | S | SAD+W | | ADR | | Sr | SAD+R | | | A |
| Slave | | | SA | | SA | | | SA | DATA | |

| | | | | | | |
|------|---|------|---|------|----|---|
| | A | | A | | /A | P |
| DATA | | DATA | | DATA | | |

I²C Standard / Fast / Fast Mode plus read communication protocol

Write Format

One Byte Write

| | | | | | | | | |
|--------|---|-------|----|-----|----|------|----|---|
| Master | S | SAD+W | | ADR | | DATA | | P |
| Slave | | | SA | | SA | | SA | |

Multiple Bytes Write

| | | | | | | | | | | |
|--------|---|-------|----|-----|----|------|----|------|----|---|
| Master | S | SAD+W | | ADR | | DATA | | DATA | | P |
| Slave | | | SA | | SA | | SA | | SA | |

I²C Standard / Fast / Fast Mode plus write communication protocol

REGISTER DESCRIPTIONS

Supplier ID Register

Address : 00h, "Supplier ID"

| Address | bit | Symbol | R/W | Init | Description |
|---------|-----|--------|-----|------|---------------------------|
| 00h | 7:0 | SID | R | 49h | Supplier ID from customer |

Chip ID Register

Address : 01h, "Chip ID"

| Address | bit | Symbol | R/W | Init | Description |
|---------|-----|--------|-----|------|-----------------------|
| 01h | 7:0 | CPID | R | 18h | Chip ID from customer |

Revision ID Register

Address : 02h, "Revision ID"

| Address | bit | Symbol | R/W | Init | Description |
|---------|-----|--------|-----|------|-----------------------------|
| 02h | 7:0 | RVID | R | 01h | Revision ID from ALSPALPINE |

Chip Config Register

Address : 11h, "Chip Config"(CCF)

| Address | bit | Symbol | R/W | Init | Description |
|---------|-----|--------|-----|------|---|
| 11h | 7:5 | RSV | R | 0h | Reserved |
| | 4 | SPIM | R/W | SPIV | SPIModeSelection |
| | 3:1 | RSV | R | 0h | Reserved |
| | 0 | SRST | R/W | 0h | Software Reset 1 : Enable Reset 0 : Normal After Software Reset completed, automatically return 0. |

Interrupt Config Register

Address : 14h, "Interrupt Config"(ICF)

| Address | bit | Symbol | R/W | Init | Description |
|---------|-----|--------|-----|------|---|
| 14h | 7:3 | RSV | R | 00h | Reserved |
| | 2 | IMLP | R/W | 0b | Intterrupt Mode 1 : Latched Mode 0 : Pulsed Mode |
| | 1 | IPPO | R/W | 1b | Drive Circuit of INT pin 1 : Push-Pull 0 : Open drain |
| | 0 | IPOL | R/W | 1b | Interrupt Polarity 1 : Active High 0 : Active Low |

REGISTER DESCRIPTIONS (Continued)

Interrupt Source Register

Address : 15h, "Interrupt Source"(ISO)

| Address | bit | Symbol | R/W | Init | Description |
|---------|-----|--------|-----|------|--|
| 15h | 7:4 | RSV | R | 00h | Reserved |
| | 3 | DRDY | R/W | 0b | Interrupt Enable for DRDY signal 1 : DRDY Enable 0 : DRDY Disable |
| | 2 | FTHS | R/W | 0b | Interrupt Enable for FIFO Threshold 1 : FIFO Threshold Enable 0 : FIFO Threshold Disable |
| | 1 | FFUL | R/W | 0b | Interrupt Enable for FIFO FULL 1 : FIFO Full Enable 0 : FIFO Full Disable |
| | 0 | RSV | R | 0b | Reserved |

FIFO Config Register

Address: 16h, "FIFO Config"(FFCF)

| Address | bit | Symbol | R/W | Init | Description |
|---------|-----|--------|-----|------|---|
| 16h | 7:6 | FFMD | R/W | 00b | FIFO Mode Control 00 : Bypass Mode 01 : Stream-to-FIFO Mode 10 : STOP-on-FULL Mode 11 : Bypass Mode |
| | 5:0 | FFTH | R/W | 00h | FIFO Threshold 0x00 : Disable the FIFO threshold 0x3F : 63 frames |

Sensor Config Register

Address : 17h, "Sensor Config"(SCF1)

| Address | bit | Symbol | R/W | Init | Description |
|---------|-----|--------|-----|------|--|
| 17h | 7 | TDIS | R/W | 0b | TEMP measurement disable 1: TEMP measurement disable 0: TEMP measurement is performed with CMM or OSM |
| | 6 | RES | R | 0b | Resolution Change 1: 0.0375uT/LSB output Range is +-1.2mT 0: 0.075uT/LSB output Range is +-2.4mT |
| | 5:4 | TAP | R/W | 10b | Measurement TAP option for CMM 00: 6bit TAP(Ultra Low Power setting) 01: 7bit TAP(Low Power setting) 10: 8bit TAP(Default setting) 11: 9bit TAP(Low Noise setting) |
| | 3:2 | MODE | R/W | 00b | Measurement Mode Selection 00: Standby Mode 01: Continuous Measurement Mode(CMM) 10: Reserve 11: One-Shot Mode(OSM) |
| | 1:0 | ODR | R/W | 00b | Output Data Rate 00: 200Hz 01: 100Hz 10: 50Hz 11: 10Hz |

REGISTER DESCRIPTIONS (Continued)

TEMP Measurement Register

Address : 1Dh to 1Eh, "TEMP Measurement Data"(TEMP)

| Address | bit | Symbol | R/W | Init | Description |
|---------|-----|--------|-----|------|---|
| 1Dh | 7:0 | TEMP | R | 7Fh | TEMP data LSB TEMP[7:0] |
| 1Eh | 7:0 | TEMP | R | 7Fh | TEMP data MSB TEMP[15:8] TEMP[15:0] 16bit signed value -40 degC : FB00h (-1280d) 25 degC : 0320h (800d) 85 degC : 0AA0h (2720d) TEMP internal initial value is 0320h (800d) = 25 degC for compensation. TEMP sensor slope is 32LSB/degC. |

Address : 1Fh to 24h, "Magnetometer Measurement Data"(MAGX, MAGY, MAGZ)

GMR Measurement Output Register

- 16bit integer and 7FFFh (+32767d) ~ 8000h (-32768d).

| Address | bit | Symbol | R/W | Init | Description |
|---------|-----|--------|-----|------|--|
| 1Fh | 7:0 | MAGX | R | 7Fh | Magnetometer X axis measreuemnt data LSB MAGX[7:0] |
| 20h | 7:0 | MAGX | R | 7Fh | Magnetometer X axis measreuemnt data MSB MAGX[15:8] |
| 21h | 7:0 | MAGY | R | 7Fh | Magnetometer Y axis measreuemnt data LSB MAGY[7:0] |
| 22h | 7:0 | MAGY | R | 7Fh | Magnetometer Y axis measreuemnt data MSB MAGY[15:8] |
| 23h | 7:0 | MAGZ | R | 7Fh | Magnetometer Z axis measreuemnt data LSB MAGZ[7:0] |
| 24h | 7:0 | MAGZ | R | 7Fh | Magnetometer Z axis measreuemnt data MSB MAGZ[15:8] |

Interrupt Status Register

Address : 25h, "Interrupt Status"(ISTA)

| Address | bit | Symbol | R/W | Init | Description |
|---------|-----|--------|-----|------|--|
| 25h | 7:5 | RSV | R | 0b | Reserved |
| | 4 | POR | R | 0b | POR complete and Software reset completed indicator 1 : completed 0 : not complete |
| | 3 | DRDY | R | 0b | Data Ready indicator 1 : Active 0 : Inactive |
| | 2 | FTHS | R | 0b | FIFO Threshold indicator FCNT >= FTHS 1 : Active 0 : Inactive |
| | 1 | FFUL | R | 0b | FIFO Full indicator FCNT = 64 1 : Active 0 : Inactive |
| | 0 | RSV | R | 0b | Reserved |

Note) The indicators are clear on read register

REGISTER DESCRIPTIONS (Continued)

FIFO Register

Address : 26h, "FIFO Count"(FCNT)

| Address | bit | Symbol | R/W | Init | Description |
|---------|-----|--------|-----|------|--|
| 26h | 7:0 | FCNT | R | 00h | The count number of FIFO data store 00h : empty 3Fh : 63 frames 40h : 64 frames (FIFO full) |

Address : 27h, "FIFO Data Register"(FOUT)

| Address | Bit | Symbol | R/W | Init | Description |
|---------|-----|--------|-----|------|---|
| 27h | 7:0 | FOUT | R | 7Fh | FIFO data output register address FIFO frame is composed 16 byte |

Frame structure

| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 |
|----------|---|---|---|---|---|---|---|------|---|--------------|----|------|----|------|----|
| Reserved | | | | | | | | Temp | | Magnetometer | | | | | |
| - | | | | | | | | TEMP | | MAGX | | MAGY | | MAGZ | |

| Byte | Bit | Symbol | R/W | Init | Description |
|------|------|--------|-----|------|---|
| 1 | 7:0 | REV | R | - | Reserved byte |
| 2 | 7:0 | REV | R | - | Reserved byte |
| 3 | 7:0 | REV | R | - | Reserved byte |
| 4 | 7:0 | REV | R | - | Reserved byte |
| 5 | 7:0 | REV | R | - | Reserved byte |
| 6 | 7:0 | REV | R | - | Reserved byte |
| 7 | 7:0 | REV | R | - | Reserved byte |
| 8 | 7:0 | TEMP | R | 7Fh | Temp measurement data low byte, if empty, output is 7Fh |
| 9 | 15:8 | TEMP | R | 7Fh | Temp measurement data high byte, if empty, output is 7Fh |
| 10 | 7:0 | MAGX | R | 7Fh | Mag X measurement data low byte, if empty, output is 7Fh |
| 11 | 15:8 | MAGX | R | 7Fh | Mag X measurement data high byte, if empty, output is 7Fh |
| 12 | 7:0 | MAGY | R | 7Fh | Mag Y measurement data low byte, if empty, output is 7Fh |
| 13 | 15:8 | MAGY | R | 7Fh | Mag Y measurement data high byte, if empty, output is 7Fh |
| 14 | 7:0 | MAGZ | R | 7Fh | Mag Z Measurement data low byte, if empty, output is 7Fh |
| 15 | 15:8 | MAGZ | R | 7Fh | Mag Z measurement data high byte, if empty, output is 7Fh |

REGISTER DESCRIPTIONS (Continued)

Sensor Action Register

'Address : 28h, "Sensor Action"(SACT)

| Address | bit | Symbol | R/W | Init | Description |
|---------|-----|--------|-----|------|---|
| 28h | 7:2 | RSV | R | 00h | Reserved |
| | 1 | MES | R/W | 0b | Magnetometer measurement. This function is available only One-Shot Mode. 1 : Performe Magnetmeter measurement. After measurement, this bit is returned 0 automatically. 0 : No action |
| | 0 | TMES | R/W | 0b | TEMP measurement. This function is available only One-Shot Mode. 1 : Performe Temperature measurement. After measurement, this bit is returned 0 automatically. 0 : No action |

REGISTER DEFINITIONS

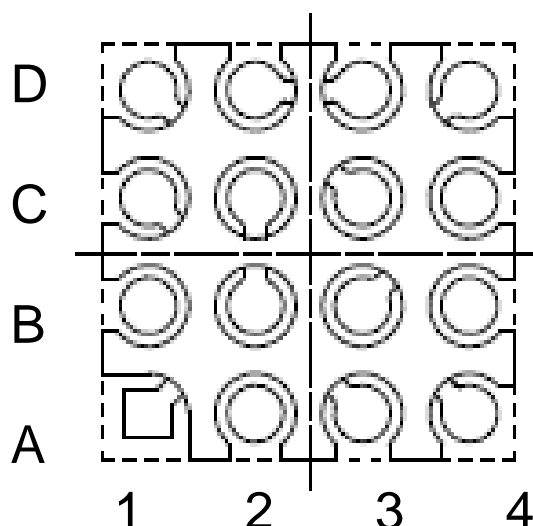
- Register addresses and definitions are as follows.
- Sensor output values are signed integer (2's complement) presentation and little Endian order.

| Addr ess | R/W | Full Name | Symbol | Bit Map | | | | | | | | Init |
|-------------|-----|------------------|--------|------------------|-----------|-----------|------|-----------|------|----------|------|------|
| | | | | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | |
| 00h | R | Supplier ID | SID | 0 | 1 | 0 | 0 | 1 | 0 | 0 | 1 | 49h |
| 01h | R | Chip ID | CPID | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 0 | 18h |
| 02h | R | Revision ID | RVID | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 01h |
| 03h | R | Reserved | | | | | | | | | | - |
| ~ | | | | | | | | | | | | |
| 10h | | | | | | | | | | | | |
| 11h | RW | Chip Config | CCF | | | | SPIM | | | | SRST | 00h |
| 12h | R | Reserved | | | | | | | | | | - |
| 13h | R | | | | | | | | | | | |
| 14h | RW | INT Config | ICF | | | | | | IMLP | IPPO | IPOL | 03h |
| 15h | RW | INT Source | ISO | | | | | DRDY | FTHS | FFUL | | 00h |
| 16h | RW | SFIFO Config | FFCF | FFMD[1:0] | | [5:0]FFTH | | | | | | 00h |
| 17h | RW | Sensor Config1 | SCF1 | TDIS | RES | TAP[1:0] | | MODE[1:0] | | ODR[1:0] | | 00h |
| 18h | R | Reserved | | | | | | | | | | - |
| 19h | R | | | | | | | | | | | |
| 1Ah | R | Reserved Config1 | RRG1 | | | | | | | | | 00h |
| 1Bh | R | Reserved Config2 | RRG2 | | | | | | | | | 00h |
| 1Ch | R | Reserved Config3 | RRG3 | | | | | | | | | 00h |
| 1Dh | R | Temp Data LSB | TEMP | TEMP[7:0] | | | | | | | | 7Fh |
| 1Eh | R | Temp Data MSB | TEMP | TEMP[15:8] | | | | | | | | 7Fh |
| 1Fh | R | Mag X LSB | MAGX | MAGX[7:0] | | | | | | | | 7Fh |
| 20h | R | Mag X MSB | MAGX | MAGX[15:8] | | | | | | | | 7Fh |
| 21h | R | Mag Y LSB | MAGY | MAGY[7:0] | | | | | | | | 7Fh |
| 22h | R | Mag Y MSB | MAGY | MAGY[15:8] | | | | | | | | 7Fh |
| 23h | R | Mag Z LSB | MAGZ | MAGZ[7:0] | | | | | | | | 7Fh |
| 24h | R | Mag Z MSB | MAGZ | MAGZ[15:8] | | | | | | | | 7Fh |
| 25h | R | INT Status | ISTA | | | | POR | DRDY | FTHS | FFUL | | 00h |
| 26h | R | FIFO Count | FCNT | | FCNT[6:0] | | | | | | | 00h |
| 27h | R | FIFO Data Reg | FOUT | FIFO output port | | | | | | | | 7Fh |
| 28h | RW | Sensor Action | SACT | | | | | | | MES | TMES | 00h |

PIN CONFIGURATION

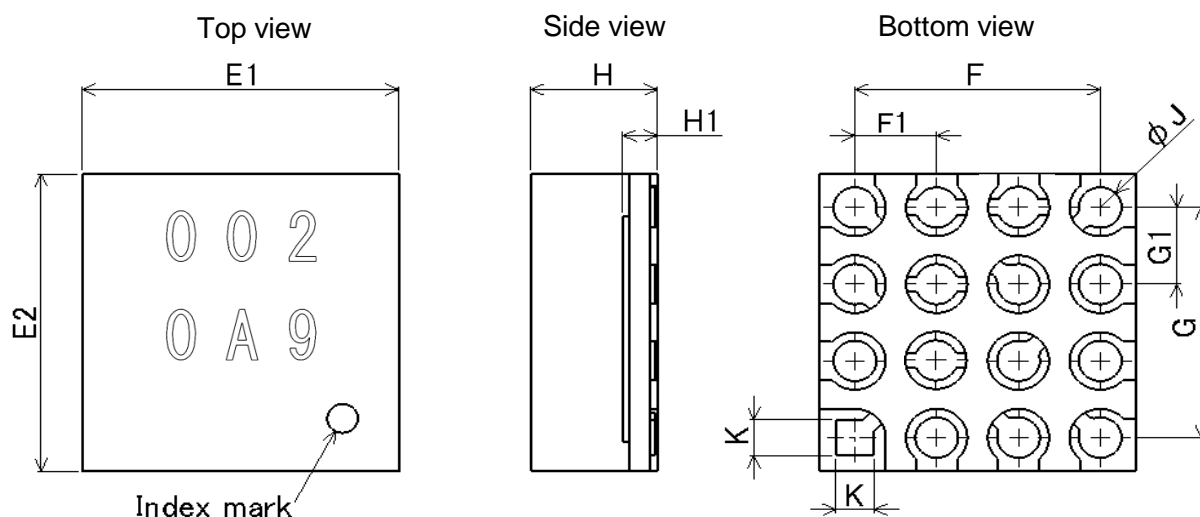
| Pin | Symbol | Type | Description |
|-----|--------|--------------------|--|
| A1 | INT | Output, CMOS | Interrupt or Data Ready Selectable push-pull / open-drain open-drain state is implemented pull-up* |
| A2 | (CSB) | (Input, CMOS) | (chip Select) |
| A3 | SCL | Input, CMOS | I2C Serial Clock (SCL) |
| A4 | SDA | Input/Output | I2C Serial Data (SDA) |
| B1 | TEST | - | Factory use only Recommend GND connect |
| B2 | NC | - | Non connect Connect GND or Floating is OK. |
| B3 | TEST | - | Factory use only Recommend GND connect |
| B4 | SA0 | Input/Output, CMOS | I2C Slave Address |
| C1 | GND | Power | Ground |
| C2 | NC | - | Non connect Connect GND or Floating is OK. |
| C3 | TRG | Input, CMOS | External Trigger Recommend GND connect |
| C4 | AVDD | Power | Power supply |
| D1 | TEST | - | Factory use only Only Floating |
| D2 | NC | - | Non connect Connect GND or Floating is OK. |
| D3 | NC | - | Non connect Connect GND or Floating is OK. |
| D4 | VDDIO | Power | Power supply for I/O |

Bottom view



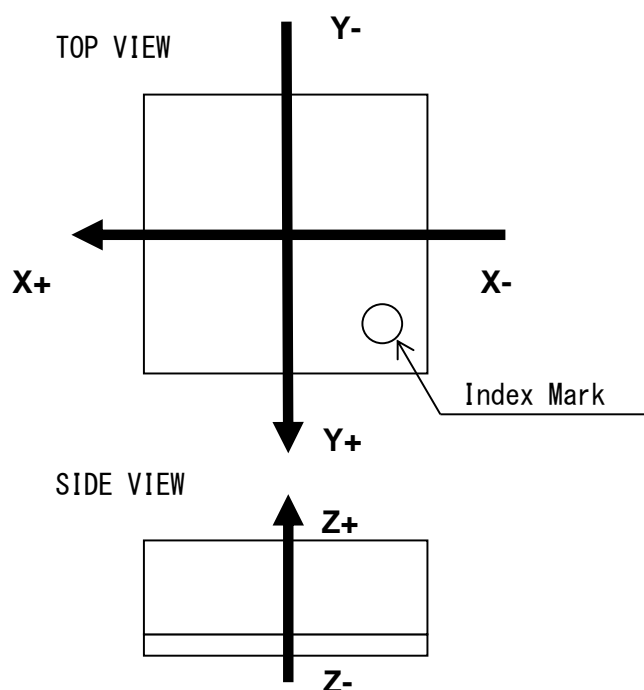
PACKAGE DIMENSIONS

| Dimension in millimeters | | | unit: mm |
|--------------------------|-------|-------|----------|
| Ref | Min. | Nom. | Max. |
| E1 | 1.50 | 1.55 | 1.60 |
| E2 | 1.50 | 1.55 | 1.60 |
| F | 1.15 | 1.2 | 1.25 |
| F1 | 0.35 | 0.4 | 0.45 |
| G | 1.15 | 1.2 | 1.25 |
| G1 | 0.35 | 0.4 | 0.45 |
| H | 0.6 | 0.62 | 0.64 |
| H1 | 0.13 | 0.16 | 0.19 |
| J | 0.185 | 0.21 | 0.235 |
| K | 0.161 | 0.186 | 0.211 |



PACKAGE DIRECTIONS

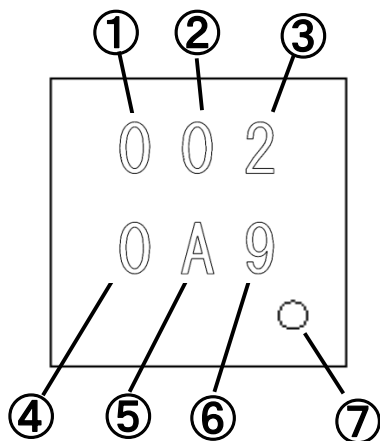
- X, Y, Z presents measurement directions of 3 axis sensor.
- Output value of each axis is positive when turned toward magnetic north.



Marking Specifications

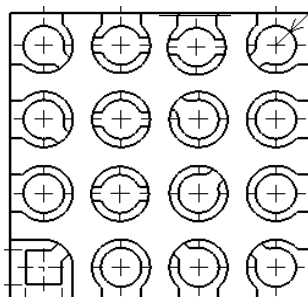
Front

top view



Back side

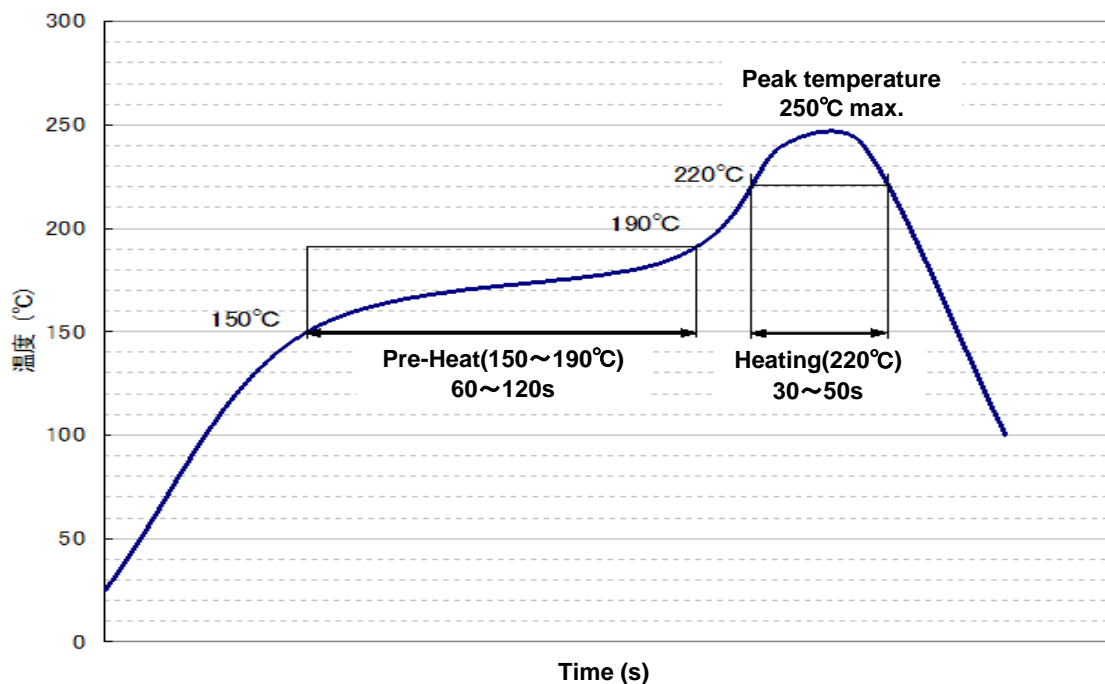
Bottom view



| No. | Item | Indication content |
|-------|------------------|--------------------|
| ① - ④ | PWB No. | 0 - 9, A - Z |
| ⑤ | Production month | 1 - 9, A, B, C |
| ⑥ | Production site | 9 |
| ⑦ | 1 Pin mark | ● |

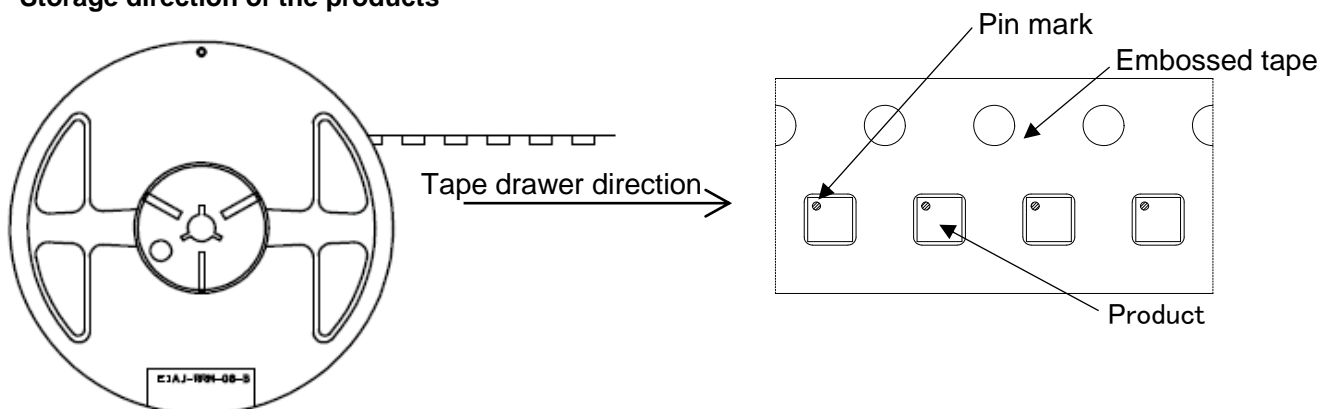
RECOMMENDED SOLDERING CONDITIONS

- The N₂ reflow is acceptable.
- Under the following conditions, the frequency of reflow soldering should be within two times.

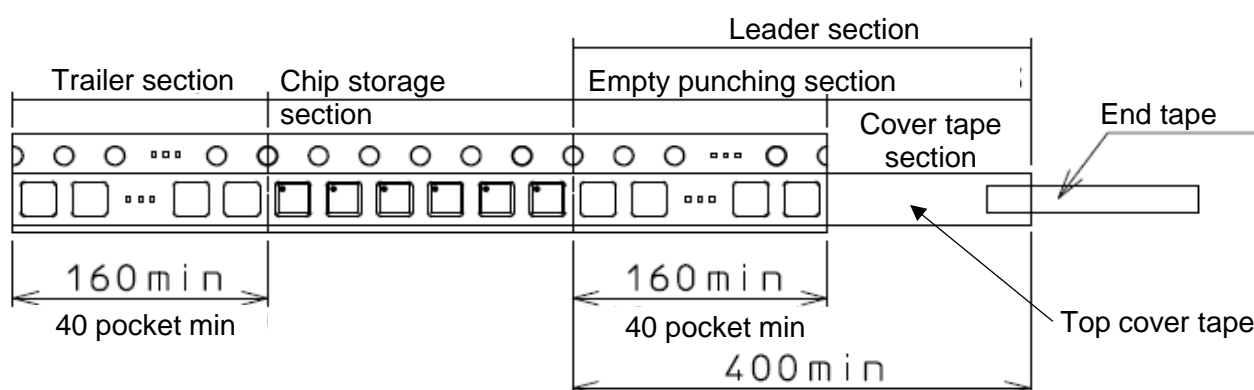


REEL AND TAPE

Storage direction of the products



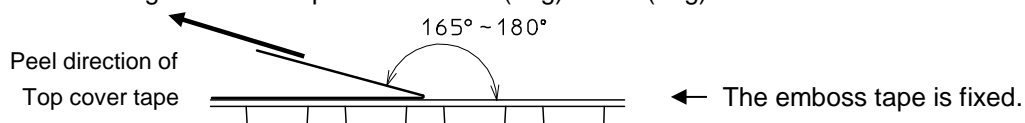
Taping



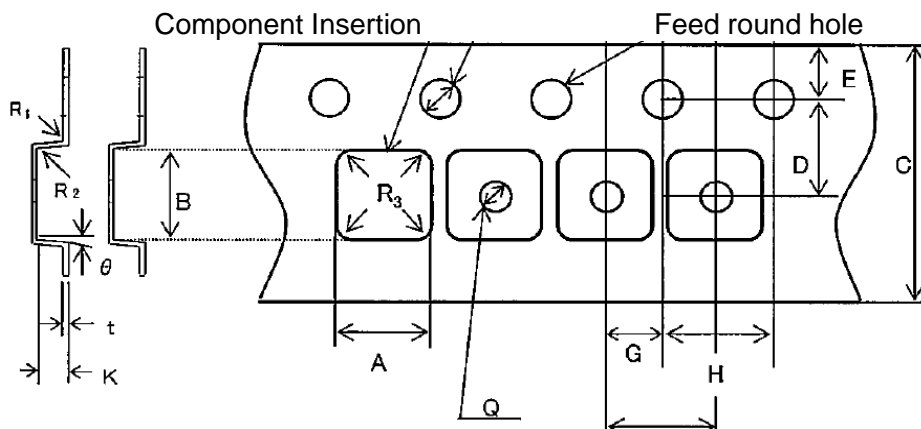
REEL AND TAPE (Continued)

Peel strength

- Peel strength of cover tape shall be 0.1N(10g)~0.7N(70g) for 300mm/min.



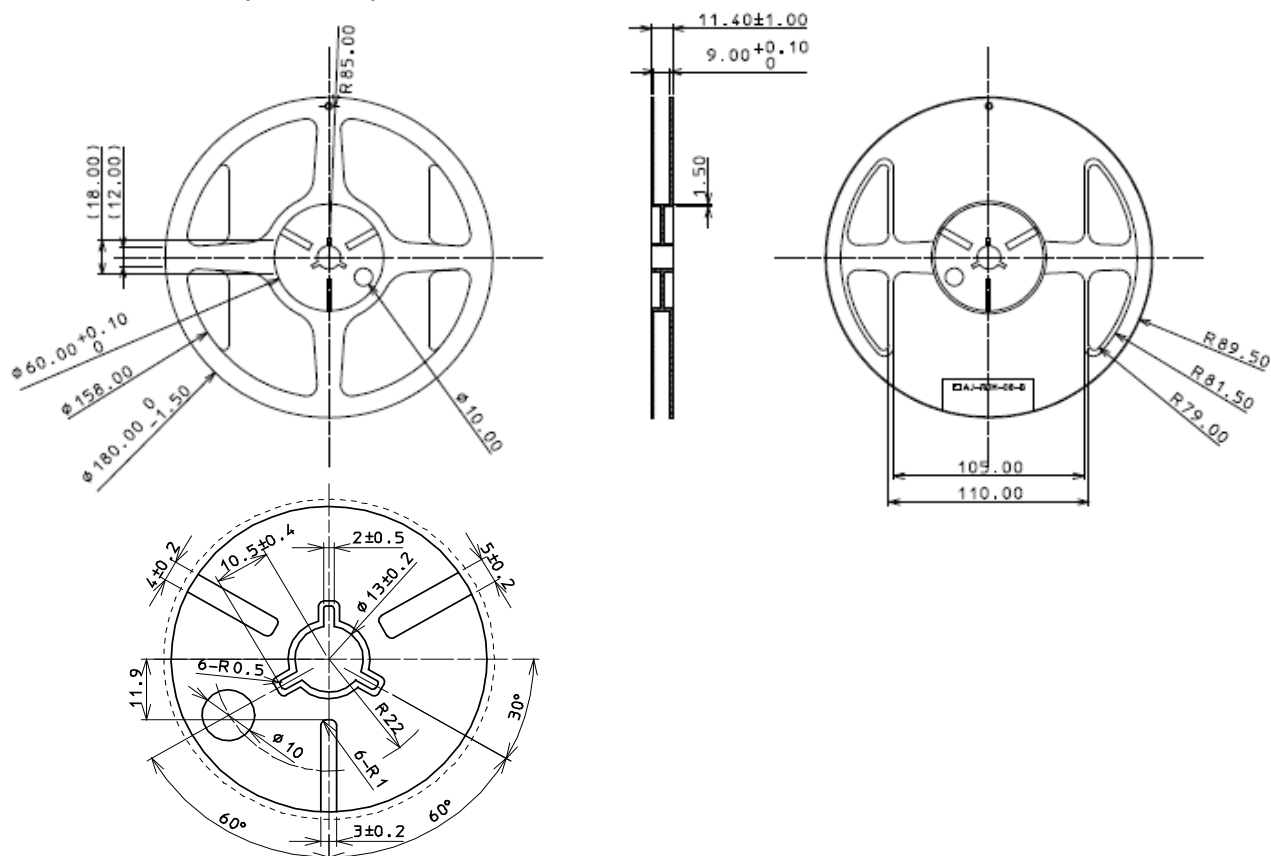
Emboss Tape Dimensions (Unit mm)



| Symbol | A | B | C | D | E | F | G | H | J | K | Q | t |
|-----------|---------|---------|---------|----------|----------|---------|----------|---------|----------------------------------|-----------|-----------|-----------|
| Dimension | 1.9±0.1 | 1.9±0.1 | 8.0±0.2 | 3.5±0.05 | 1.75±0.1 | 4.0±0.1 | 2.0±0.05 | 4.0±0.1 | 1.5 ^{+0.1} ₀ | 0.75±0.05 | 0.50±0.05 | 0.20±0.05 |

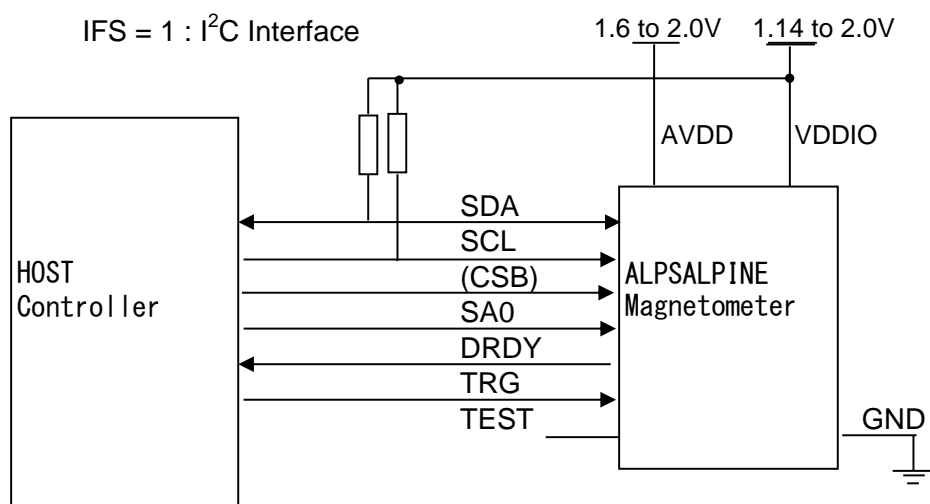
| R ₁ | R ₂ | R ₃ | θ |
|----------------|----------------|----------------|--------|
| 0.3MAX | 0.3MAX | 0.3MAX | 3° MAX |

Reel Dimensions (Unit : mm)

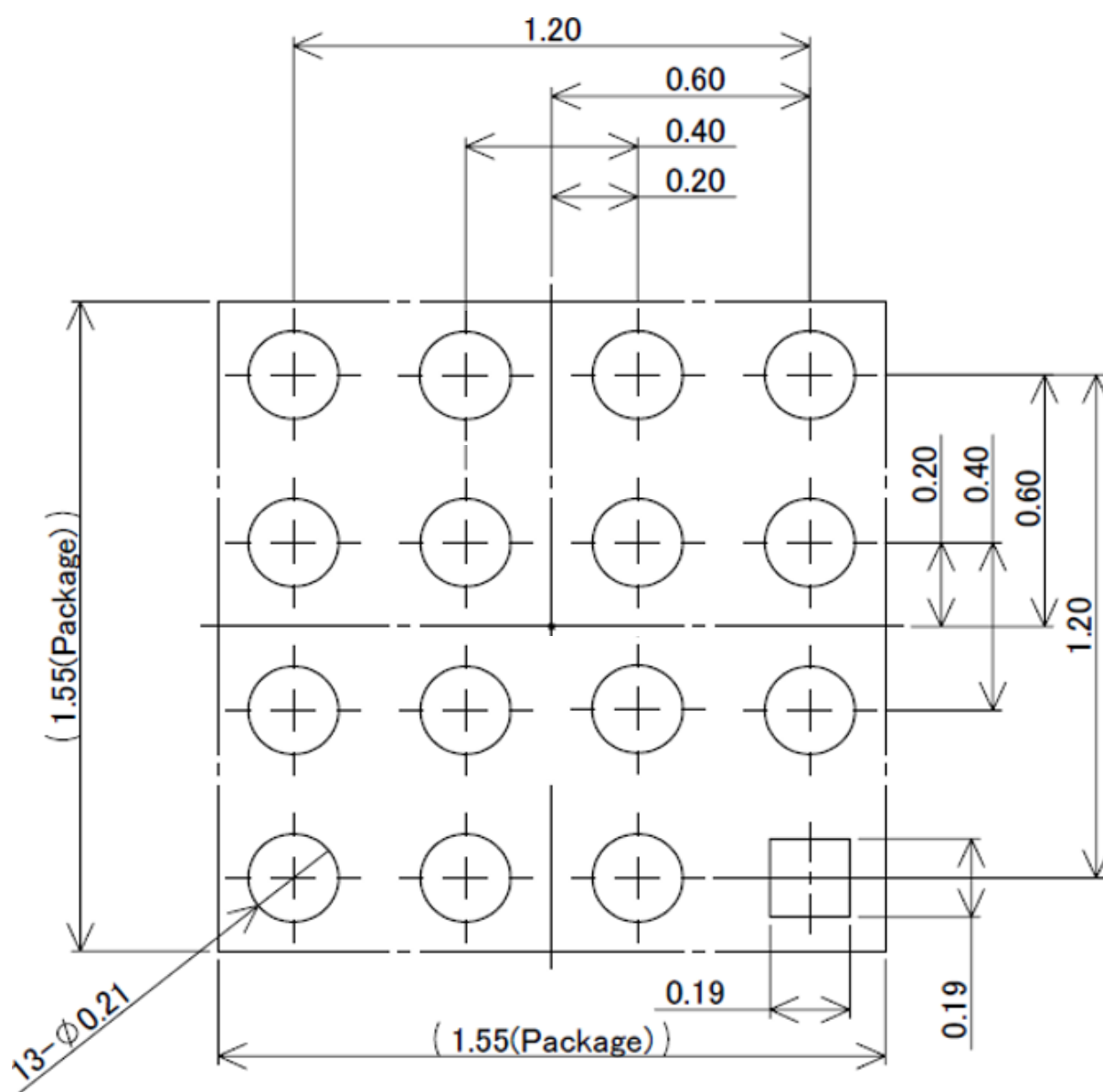


CONNECTION EXAMPLE

I2C Interface connection block diagram



RECOMMENDED LAND PATTERN



Asking that exports this product

- 1 . For the export of products which are controlled items subject to foreign and domestic export laws and regulations, you must obtain approval and/or follow the formalities of such laws and regulations.
- 2 . Products must not be used for military and/or antisocial purposes such as terrorism, and shall not be supplied to any party intending to use the products for such purposes.
- 3 . Unless provided otherwise, the products have been designed and manufactured for application to equipment and devices which are sold to end-users in the market, such as AV (audio visual) equipment, home electric equipment, office and commercial electronic equipment, information and communication equipment or amusement equipment. The products are not intended for use in, and must not be used for, any application of nuclear equipment, driving control equipment for aerospace or any other unauthorized use.

With the exception of the above mentioned banned applications, for applications involving high levels of safety and liability such as medical equipment, burglar alarm equipment, disaster prevention equipment and undersea equipment, please contact an Alps Alpine sales representative and/or evaluate the total system on the applicability. Also, implement a fail-safe design, protection circuit, redundant circuit, malfunction protection and/or fire protection into the complete system for safety and reliability of the total system.

- 4 . Before using products which were not specifically designed for use in automotive applications, please contact an Alps Alpine sales representative.